



Definitions and Predictions of Integrability for Difference Equations

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Symmetries and Integrability of Difference Equations
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Although complete integrability is structurally unstable, many properties persist in nearby non-integrable systems.

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- Need to discretize continuous equations for numerical analysis
- Interesting mathematics in the background, e.g., elliptic functions.
- Continuum integrability is well established, all easy things have already been done. Discrete integrability relatively new, still new things to be discovered.

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Given x_0, x_1 we can compute x_n for all $n \in \mathbb{Z}$.

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In these lectures: we take a look on various meanings of integrability for difference equations, and the possible associated algorithmic methods to identify (partial) integrability.

Map or functional equation

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Different settings bring in different properties, tools and results.

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Logistic map

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Sensitive dependence on the initial value:

$$\frac{dy_n}{dc_0} = \frac{1}{2} 2^n \sin(2^n c_0)$$

Thus error grows exponentially: “chaotic”.

Integrable discretization? ($O\Delta E$)

Example: ODE

$$\frac{du}{dt} = \alpha u(1 - \beta u), \quad (*)$$

with solution

$$u(t) = \frac{u_0}{\beta u_0 + (1 - \beta u_0)e^{-\alpha t}}.$$

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Naive discretization:

$$\frac{du}{dt} \approx \frac{u(t + \Delta t) - u(t)}{\Delta t} \Rightarrow$$

$$u(t + \Delta t) - u(t) = \Delta t \alpha u(t)(1 - \beta u(t)). \quad (d1)$$

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Let $u(t) = u(n\Delta t) = \frac{a}{\alpha\beta\Delta t} x_n$, $a = 1 + \alpha\Delta t$, then we get

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This is the logistic equation which can be chaotic.

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Second attempt:

$$u(t + \Delta t) - u(t) = \Delta t \alpha u(t + \Delta t)(1 - \beta u(t)). \quad (d2)$$

or after solving for $u(t + \Delta t)$

$$u(t + \Delta t) = \frac{u(t)}{(1 - \alpha \Delta t) + \alpha \beta \Delta t u(t)}$$

Why should we even consider this?

The original equation

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can be **linearized** with $u = 1/(w + \beta)$ to

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Discretize the linearized equation as

$$w(t + \Delta t) - w(t) = -\alpha \Delta t w$$

and then substituting $w = -\beta + 1/u$ we get

$$u(t + \Delta t) - u(t) = \alpha \Delta t u(t + \Delta t)(1 - \beta u(t)). \quad (d2)$$

The difference equation for w

$$w(t + \Delta t) - w(t) = -\alpha \Delta t w(t)$$

is solved by

$$w(t + n\Delta t) = (1 - \alpha \Delta t)^n w(t)$$

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Now the discrete solution samples the continuum solution.

$$u(t) = \frac{u_0}{\beta u_0 + (1 - \beta u_0)e^{-\alpha t}}.$$

Examples and continuum limits

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Let us take the continuum limit: set

$$\epsilon n = z, \quad x_n = f(z), \quad x_{n\pm 1} = f(z \pm \epsilon), \quad \epsilon \rightarrow 0, \quad n \rightarrow \infty, \quad \epsilon n \text{ fixed}$$

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This yields

$$3f + \epsilon^2 f'' = \frac{\alpha + \beta z / \epsilon}{f} + b.$$

To get rid of the denominator we must take

$$f(z) = c_1 + c_2 \epsilon^\kappa y(z),$$

and expand. The power $\kappa > 0$ is to be determined.

$$3c_1 + 3c_2 \epsilon^\kappa y(z) + 3c_2 \epsilon^{2+\kappa} y'' = b + \frac{1}{c_1} (\alpha + \beta z / \epsilon) \left(1 - \frac{c_2}{c_1} \epsilon^\kappa y + \left(\frac{c_2}{c_1} \right)^2 \epsilon^{2\kappa} y^2 \dots \right)$$

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To balance terms we must take $\kappa = 2$, then we get

$$\epsilon^0: 3c_1 = b + \frac{1}{c_1} \alpha$$

$$\epsilon^2: 3c_2 = -\frac{c_2^2}{c_1^2} \alpha$$

leading to

$$c_1 = \frac{b}{6}, \quad \alpha = -\frac{b^2}{12}$$

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Finally at ϵ^4 we get the first Painleve equation

$$y'' = 6y^2 + z,$$

if we choose

$$c_2 = -\frac{b}{3}, \quad \beta = -\frac{b^2}{18} \epsilon^5.$$

Constants of motion for continuous ODE

Definition of **Liouville integrability**:

A Lagrangian $L(\dot{q}, q)$, where q is N -dimensional, is integrable if there are N constants of motion (CM) $I_k(\dot{q}, q)$ (L one of them) such that the I_k

- 1 are independent
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The role of a CM (in continuous and discrete world): it restricts the available phase space and thereby makes the motion more predictable.

Relation of CM to the equation:

$$\frac{dI(\dot{q}, q)}{dt} = \sum_i \frac{\partial I}{\partial \dot{q}_i} \ddot{q}_i + \sum_i \frac{\partial I}{\partial q_i} \dot{q}_i.$$

The RHS should vanish when we impose the equations of motion of the type

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N=1: Any given $I(\dot{q}, q)$ is a CM for some equation $\ddot{q} = \dots$

The basic difficulty in the discrete case

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Consider the discrete equivalent, a 3-point equation in

$$x \equiv u_{n+1}, y \equiv u_n, z \equiv u_{n-1}.$$

The equation relating x, y, z should be linear in x and z to guarantee well defined evolution.

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How could this produce an equation linear in x, z if K is nonlinear?

The lack of Liebnitz rule bites us again!

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Then we may try a biquadratic K :

$$K(x, y) := c_5 x^2 y^2 + c_4 xy(x + y) + c_3 xy + c_2(x^2 + y^2) + c_1(x + y). \quad (*)$$

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We get

$$\frac{K(x, y) - K(y, z)}{x - z} = c_1 + c_2(x + z) + c_3 y + c_4 y(x + y + z) + c_5 y^2(x + z),$$

from which we get an equation having (*) as CM.

$$x + z = \frac{c_4 y^2 + c_3 y + c_1}{c_5 y^2 + c_4 y + c_2}$$

The QRT map

Can we generalize?

Yes: take a rational biquadratic:

$$K(x, y) = \frac{c_5 x^2 y^2 + c_4 xy(x + y) + c_3 xy + c_2(x^2 + y^2) + c_1(x + y)}{d_5 x^2 y^2 + d_4 xy(x + y) + d_3 xy + d_2(x^2 + y^2) + d_1(x + y)}$$

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Direct computation shows that this is a CM for the [symmetric version of the Quispel-Roberts-Thomson \(QRT\) map](#):

$$x = \frac{f_1(y) - f_2(y)z}{f_2(y) - f_3(y)z}$$

where f_i are certain specific quartic polynomials.

This contains almost all 3-point maps.

Some examples of QRT

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One of the discrete Painlevé equation is $dP_{\text{III}} (f_2 = 0)$:

$$x_{n+1}x_{n-1} = \frac{cd(x_n - a\lambda^n)(x_n - b\lambda^n)}{(x_n - c)(x_n - d)}.$$

This is a **nonautonomous** equation,
i.e., it contains explicit n -dependence.

The HKY generalization

The Hirota-Kimura-Yahagi (HKY) generalization: Quartic CM

Consider

$$K(x, y) = \frac{2xy}{x^2 + y^2 + \beta^2},$$

Then we have

$$K(x, y) - K(y, z) = \frac{-2y(x-z)[xz - (y^2 + b^2)]}{(x^2 + y^2 + b^2)(y^2 + z^2 + b^2)}$$

leading to the 3-point equation

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But we also have

$$K(x, y) + K(y, z) = \frac{2y(x+z)[xz + (y^2 + b^2)]}{(x^2 + y^2 + b^2)(y^2 + z^2 + b^2)}$$

How can this be interpreted?

It seems that in the second case K is conserved “up to sign”.
 Then $K(x, y)^2$, which is quartic, should be a genuine invariant.
 Indeed:

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Other HKY-type invariants are known.

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What about growth analysis?

Recall that difference equations can trivially be solved step by step, what is the growth of the resulting expression?

Singularity analysis for difference equations

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Using this principle it has been possible to find discrete analogies of Painlevé equations. [Ramani, Grammaticos and JH, *Phys. Rev. Lett.* 67 (1991) 1829, and many others]

Singularity confinement in practice

Consider first the autonomous case of dPI

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To resolve “ $\infty - \infty$ ”:

assume $x_0 = \epsilon$ (small) and redo the calculations.

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The **singularity pattern** is $\dots, 0, \infty, -\infty, 0, \dots$

Non-confined singularity

A worst case example:

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In general

$$x_k = k\frac{a}{\epsilon} + \dots,$$

and the singularity is **not confined**, ever.

Furthermore: there are **no ambiguities**.

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Problem: x_4 should start like $\mathbf{u} + \dots$!

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The condition for singularity confinement at this **same** step is:

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In general, with a_n as in (*) the singularity is confined, and

$$x_4 := \frac{\mathbf{u}(\alpha + \gamma) + 2b\beta}{\alpha + 3\beta - \gamma} + O(\epsilon),$$

in particular, if $\beta = \gamma = 0$ (i.e., $a_n = \alpha$), $x_4 = \mathbf{u} + \dots$

Singularity confinement in projective space

The singularities reveal their nature best in projective space,
where $(u, v, f) \approx (\lambda u, \lambda v, \lambda f)$, $\lambda \neq 0$

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Then homogenize by substituting $x_n = u_n/f_n$, $y_n = v_n/f_n$:

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Then clearing denominators yields a **polynomial** map in \mathbb{P}^2

$$\begin{cases} u_{n+1} &= -u_n(u_n + v_n) + f_n(a_n f_n + b u_n), \\ v_{n+1} &= u_n^2, \\ f_{n+1} &= f_n u_n. \end{cases}$$

Note: default growth of degree (= **complexity**): $\deg(u_n) = 2^n$

The sequence that led to a singularity was

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In projective space we have

$$\begin{pmatrix} 0 \\ \mathbf{u} \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix},$$

The last term is a true singularity, since it is not in \mathbb{P}^2 .

For the detailed ϵ study with $x_{-1} = \mathbf{u}$, $x_0 = \epsilon$ we have

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$$\begin{pmatrix} x_1 \\ x_0 \\ 1 \end{pmatrix} \approx \begin{pmatrix} u_1 \\ v_1 \\ f_1 \end{pmatrix} = \begin{pmatrix} a_0 + (-\mathbf{u} + b)\epsilon + \dots \\ \epsilon^2 \\ \epsilon \end{pmatrix}.$$

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$$\begin{pmatrix} u_4 \\ v_4 \\ f_4 \end{pmatrix} = \begin{pmatrix} \epsilon^2 a_0^6 A_3 + \epsilon^3 a_0^5 (b(4A_3 + a_0 - a_2) - \mathbf{u}(6A_3 + a_0)) + \dots \\ \epsilon^4 a_0^4 A_2^2 + \dots \\ -\epsilon^3 a_0^5 A_2 + \dots \end{pmatrix}$$

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This is the crucial point of singularity confinement.

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If $A_3 = 0$, $A_2 \neq 0$ then ϵ^3 is a common factor and can be divided out and then the $\epsilon \rightarrow 0$ limit yields

$$\begin{pmatrix} u_4 \\ v_4 \\ f_4 \end{pmatrix} = \begin{pmatrix} (a_0(\mathbf{u} - b) + a_2 b) \\ 0 \\ a_3 \end{pmatrix}.$$

Thus we have emerged from the singularity and in particular recovered the initial data \mathbf{u} .

- The cancellation of the common factor ϵ^3 **removes the singularity**.
- Any cancellation also **reduces growth of complexity**, as defined by the degree of the iterate.

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The precise amount of cancellation will be crucial.

- growth is linear in $n \Rightarrow$ equation is linearizable.
- growth is **polynomial** in $n \Rightarrow$ equation is **integrable**.
- growth is **exponential** in $n \Rightarrow$ equation is **chaotic**.

Singularity confinement is not sufficient

Counterexample (JH and C Viallet, PRL 81, 325 (1999))

$$x_{n+1} + x_{n-1} = x_n + \frac{1}{x_n^2}.$$

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Epsilon analysis of singularity confinement:

Assume $x_{-1} = \mathbf{u}$, $x_0 = \epsilon$ and then

$$x_1 = \epsilon^{-2} - \mathbf{u} + \epsilon,$$

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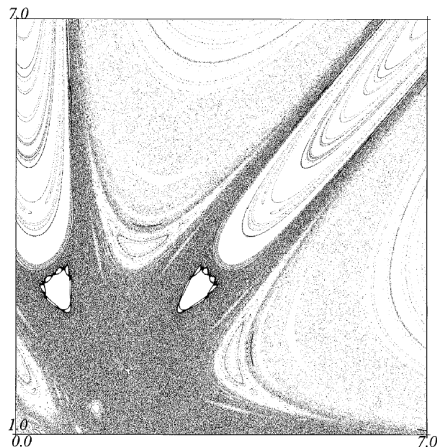
$$x_4 = \mathbf{u} + 3\epsilon + O(\epsilon^3),$$

Thus singularity is confined with pattern $\dots, 0, \infty, \infty, 0, \dots$.

Furthermore, the initial information \mathbf{u} is recovered in x_4 . OK?

No! The HV map shows numerical chaos

$$x_{n+1} + x_{n-1} = x_n + \frac{7}{x_n^2}$$



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For the previous chaotic model the degrees grow as

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For the previous Painlevé equation the degrees grow as

$$1, 2, 4, 8, 13, 20, 28, 38, 49, 62, 76, \dots$$

which is fitted by $d_n = \frac{1}{8}(9 + 6n^2 - (-1)^n)$. [JH and Viallet, Chaos, Solitons and Fractals, **11**, 29-32 (2000).]

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- Diophantine integrability (numerically fast) (Halburd)